Application of the Fuzzy Method in the Design of Control and Monitoring Systems for Flood Canal Pump Houses

Lukman Medriavin Silalahi*¹, **Linggar Amnesta Virgian**² ^{1,2}Program Studi Teknik Elektro, Universitas Mercu Buana E-mail: *1<u>lukman.medriavin@mercubuana.ac.id</u>, ²<u>linggar.vir@outlook.com</u>

Abstract

The purpose of making a prototype of the canal to flood the pump house is namely as a means of ideas that may later be applied to the pump house in Indonesia. At the end of this task will be made protorype flood canal house pump with which it can work according to the speed of the incoming flow and the height of the water in the canal, on hulu there are 1 pump 12V which will drain the water into the canal and also waterflow as a tool that can detect the incoming flow. At the pump house there are 3 pump and 1 water level which will work according to the inflow and the height of the channel. Fuzzy Logic is one method of system control can provide decision that resembles the human decision. In the design process of this plant, used a system of development control of the fuzzy logic system using Arduino. It is intended for a design on the plant control system and monitoring of the pump house flood canal. The use of the Speed Controller PWM on the circuit can work well in regulating the pump speed in the work. Pump 1 and pump 2 has a maximum value of the PWM 144 that can remove water 180 ml that works on low currents and are and sodetan have the value of the PWM to 255 that can get water out of 318 ml of working on a heavy flow.

Keywords — Arduino, detection system flow, home pump, sensors, water level

1. INTRODUCTION

A flood canal is a canal made by humans to control flood disasters due to overflowing of water flows or rivers. In general, a flood canal is part of a river flow with a widening or deepening in certain parts. The purpose of making a flood canal is to divert (partially or completely) the flow from a river to another place. This diversion is part of the overall flood control system. Apart from being used as flood control, flood canals can also function as transportation and trade routes. In the Flood Canal, a pump house is needed which functions as a means of drainage, namely a complementary building which is a building that helps regulate and control the rainwater flow system so that it is safe and easy to pass through the channel.

The role of electronics is as a support tool that utilizes various components into a unified system that is integrated with a data processor containing a program so that it can provide instructions for carrying out work to various tools such as detectors and sensors connected to an electrical source. Waterflow sensor is a sensor that can read the flow of water in a place. This sensor works to read the rotational speed of the rotor which is caused by the speed of water flow.

An increase in water level can occur at any time if the water flow that enters the flood canal is high, if it is not monitored and the flood canal, the excess water discharge will cause water to spill out of the canal which will flood the surrounding area. To minimize these undesirable things, a microcontroller-based data processing method using electronic media is integrated into the monitoring system by utilizing a water level sensor with the fuzzy logic method.

2. RESEARCH METHOD

This research study discusses control using the fuzzy method and on-off control using the automation method. Figure 1 shows the effort in developing an automatic monitoring and control system for flood canal pump houses, namely conducting a literature study as an application of the proposed research method.



Figure 1. Literature review

The process for converting non fuzzy variables (numeric variables) into fuzzy variables (linguistic variables). For the fuzzification process, either the crisp input or crisp output variables are divided into one or more fuzzy sets :

1. Membership Functions of Water Flow Input Variables

Figure 2 show that the water flow input variable, it is divided into 3 membership groups to find the membership value, the sets are low, medium and heavy. And for membership used in the form of water flow values, namely low (0-180), medium (140-360) and heavy (270-500). Following is Figure 3.11 the membership function of water currents.

2. Membership functions of the Input variable threshold

Figure 3 show that input variable the threshold is divided into 2 membership sets to find the membership value, the set is normal and dangerous. And for the degree of membership used, namely normal (0) and hazard (1). The following figure 3. threshold membership function.



Figure 2. Water Flow Membership Function



Figure 3. Threshold Membership Function



Figure 4. Pump Output Membership Function

3. Pump Output Variable Membership Functions

Figure 4 show that the pump output variable is the action of 3 water pumps in the channel, the variable is divided into 4 membership sets to find the membership value, the set is pump 1 from low current level, pump 2 from medium current level and sodetan from heavy current level. The following is a picture of 4 pump output membership functions.



Figure 5. flowchart of Research

Figure 5 shows flowcharts design, to clarify how the workflow design as a whole.

- 1. The series starts with the input of the power source voltage to turn on the whole series
- 2. The water will be flowing through the water flow sensor that will read the current speed of incoming containers.
- 3. The Data read by the sensors water flow will be forwarded to the Arduino to be validated. Then this data will control the pump automatically, if the current entering any alone for not touching the sensor water level then the pump will not turn on.
- 4. If the water in the canals touch sensor water level then the pump will turn on which will adjust the current on the water flow sensor.
- 5. The flow of water entering the canal more than 360ml/min then it will turn on all the pumps on the channel and also turn on the pump sodetan into the canal 2.
- 6. The water in the canal 2 touch sensors water level or on the verge of the normal range then it will turn on the pump on channel 2.

3. RESULTS AND DISCUSSION

This chapter will discuss the test steps and the results obtained from the application of the Fuzzy Method in the Design of Control and Monitoring Systems for Flood Canal Pump Houses.

The result of designing this tool is an aklirik container with dimensions of 25 cm x 30 cm for placing the components used. In this container there are components including the Arduino Mega 2560, 5A PWM Speed Controller, Stepper Motor Driver and also a Power Supply. In the upstream water, there is a 12v pump to drain water into the canal container and

there is also a water flow to measure the speed of the incoming current for and this is shown in Figure 6.



Figure 6. Hardware Design Results

Form1			Form1	
COM4 COM3 COM5 COM5 is connected. Water Flow		● Kanal 1 ○ Kanal 2	COM4 COM3 COM5 COM6 is connected. Water Level	○ Kanal 1 ④ Kanal 2
Water Level	0.00			250.00
Pompa 1	Pompa 2	Sodetan	Pompa 1	Pompa 2
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180.00	0.00		250.00	0.00

Figure 7. Monitoring Design Result

Figure 7 shows about the tests that have been carried out in 4 conditions in the pump line 1 which will be supplied with a low current of less than 180 ml / minute. The measurement results can be seen in Table 1.

Table 1. Test results : Low now					
Condition	Flow input (ml)	Pump 1 (ml)	Pump 2 (ml)	Sodetan	Criteria
1	-	-	-	-	Safe
2	138,00	-	-	-	Safe
1	115,00	115,00	-	-	Danger
2	-	180,00	-	-	Danger

 Table 1. Test results : Low flow

After testing at low currents can be diliat the results in the table above are obtained analysis here:

1. In the first condition of water flow (inflow) 0 ml and the water level (the threshold) off/safe then all pumps.

- 2. On the condition of the to-2 water flow (inflow) 138 ml and water level (the threshold) is off, all pumps will also be off.
- 3. On the condition of the to-3 water flow (inflow) 115 ml and water level (the threshold) danger then pump 1 will be active to follow the magnitude of the current in the water flow and pump 2 & sodetan dead.
- 4. On the condition of the to-4 water flow (inflow) 0 ml and the water level (the threshold) Danger then pump 1 will be active with the full force of 180 ml, pump 2 & sodetan off.

In this test, it was carried out with 4 conditions in channel 1 which would be flowed with a moderate current, namely between 140 ml / minute to 360 ml / minute. The results of measurements can be seen in Table 2.

Condition	Flow input (ml)	Pump 1 (ml)	Pump 2 (ml)	Sodetan	Criteria
1	-	-	-	-	Safe
2	284,33	-	-	-	Safe
1	315,00	180,00	135,00	-	Danger
2	-	180,00	-	-	Danger

 Table 2. Test results : Medium flow

After testing the medium water flow type, the results can be seen in Table 2, the following analysis is obtained:

- 1. In the first condition of water flow (inflow) 0 ml and the water level (the threshold) is safe then all pumps.
- 2. On the condition of the to-2 water flow (inflow) 284 ml but the water level (the threshold) is still in a state OFF/safe then all the pump still off.
- 3. On the condition of the to-3 water flow (inflow) 315 ml and water level (the threshold) in the state of ON/danger then pump 1 will be active with the full force of 180 ml, pump 2 will also be active will be issued a current of 135 ml of the remaining amount of current that can not be taken of the pump 1 and sodetan in the state OFF.
- 4. On the condition of the to-4 water flow (inflow) 0 ml and water level (threshold) ON/danger then pump 1 will be active with the full force of 180 ml, pump 2 & sodetan OFF.

In this test, it is carried out with 4 conditions in channel 1 which will be flowed by heavy currents, namely above 360 ml / minute. The results of measurements can be seen in Table 3.

Table 5. Test results . Then now					
Condition	Flow input (ml)	Pump 1 (ml)	Pump 2 (ml)	Sodetan	Criteria
1	-	-	-	-	Safe
2	507,00	-	-	-	Safe
1	945,00	180,00	180,00	318	Danger
2	-	180,00	-	-	Danger

Table 3. Test results : High flow

After testing the high water flow type, the results can be seen in Table 3, the following analysis is obtained:

- 1. In the first condition of water flow (inflow) 0 ml and the water level (the threshold) is safe then all pumps.
- 2. On the condition of the to-2 water flow (inflow) 284 ml but the water level (the threshold) is still in a state OFF/safe then all the pump still OFF.
- 3. On the condition of the to-3 water flow (inflow) 315 ml and water level (the threshold) in the state of ON/danger then pump 1 will be active with the full force of 180 ml, pump

2 will also be active will be issued a current of 135 ml of the remaining amount of current that can not be taken of the pump 1 and sodetan in the state OFF.

4. On the condition of the to-4 water flow (inflow) 0 ml and water level (threshold) ON/danger then pump 1 will be active with the full force of 180 ml, pump 2 & sodetan OFF.

In the composition of the combination rule for the 3 time trial on the second input provides aggregation action of water flow, which is where the to supply water into the container canal. If the water is already touching the limit of danger then it will give the command to activate the pump at the pump house which will drain the water up to the safe limit (water level off). The experiment will be carried out 3 times, i.e. at low current, medium and heavy. The Output in the fuzzy this is the value of PWM to regulate the speed of the pump to remove the water. Analysis of low flows can be viewed at Figure 8.



Figure 8. Analysis Matlab Low Current

Experiments on flow low water flow are given a flow of 130 ml and the condition of the water level is active then the PWM output obtained 103

The Formula Pump P = PWM/factor P = 103/0.8 = 128 mlPWM output on the arduino PWM = WF * factor = 130 * 0.8 = 104Difference = PWM Matlab/PWM Arduino = 103/104= 0.9 % In the experiment, low current output the resulting Matlab to drive the pump of 128 ml with PWM 103. At the output of the arduino PWM generated is 104 which will only turn on pump 1. On this analysis there is a difference of 0.99 %.



Figure 9. Analysis Matlab Medium Current

The second experiment in Matlab as in figure 9 that the flow is water flow given the current 248 ml and the condition of the water level is active then the PWM output obtained 193.

The Formula Pump P = PWM/factor P = 193/0.8 = 241 mlPWM output on the arduino PWM = WF * factor = 248 * 0.8 = 198Difference = PWM Matlab/PWM Arduino = 193/198= 0.97 %

In this experiment the resulting output Matlab to drive the pump amounted to 241 ml with PWM 193. On the total outputs of the arduino PWM generated is 198, in the current are these then the pump 1 and pump 2 are each 99 PWM/pump. On this analysis there is a difference 0,97 %



Figure 10. Analysis Matlab High Current

On the third in Matlab can be seen in Figure 10, namely the swift current where the water passes through the water flow above 360 ml, then it will issue a PWM to the fullest. For the calculation of the pump 1, pump 2 and sodetan used equations formula. On pump 1 (P1) & pump 2 (P2) set the maximum PWM 144 produce 180 ml/min and spatula (S) maximum PWM of 255 produces 318,9 ml/sec.

Max PWM P1 & P2 = 144 Max PWM S = 255 P1 & P2 = PWM/factor = 144/0,8 = 180 ml S = PWM/factor = 255/0,8 = 318,8 ml

4. CONCLUSION

Based on the testing and analysis that has been done, it can be concluded:

- 1. In monitoring channel status, the MS monitoring system can be used. Visual Studio with serial cable to see the incoming water flow, threshold and also the number of active pumps which can monitor the status of channel 1 & channel 2 in real time.
- 2. Testing the control system for pump house performance successfully states the normal threshold and the hazard threshold detected at the Water Level and the incoming current including low current, medium current and also heavy current can be adjusted according to the performance of the pump housing.
- 3. The use of a PWM Speed Controller in the circuit can work well in regulating the speed of the incoming current in the channel. Pump 1 & pump 2 have a maximum

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PWM value of 144 which can discharge 180 ml of water which works at low and medium currents and the sodetan has a PWM value of 255 which can discharge 318 ml of water which works on heavy currents.

4. For the calculation of the fuzzy calculations in the system based on the Matlab calculation and Arduino program calculations there is a difference of 0.9%.

5. SUGGESTED

Based on the results of the final project that has been carried out and the conclusions obtained, the suggestions for further research are as follows:

- 1. To design a water level system, better components can be used, the water level used does not work effectively because when the water has dropped, the remaining water is still attached to the water level surface which makes it difficult to analyze the water level status.
- 2. Using a better pump, because of the 5V pump on the market, the quality of the pump's performance easily decreases so that the value of the water released is often inconsistent. For pumps, you can use a 12V pump which is more stable and can release more water.
- 3. In terms of monitoring views made by MS. Visual Studio still looks simple, the system and monitoring can also be developed with a wireless system and thingspeak so that it can be monitored remotely.

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