

Three Axis Deviation Analysis on CNC Milling Machine

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3

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Abstract

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I. Introduction

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Since the beginning of industrial revolution, there has been dramatic increase in manufacturing quality and quantity by the application of industrial mechanization, from steam powered machines to modern days automation [1]. Today, there is greater demand for higher quality and quantity products and services which consequently requires manufacturing complexity and better quality of machining which makes industrial equipment construction more complicated [2]. In developed countries, the slowing down of population growth and aging population cause shortage in man power for industry. Other common problems nowadays are the depleting natural resources and shortening product life cycle[3]. All those problems are tried to

32
1 be overcome by implementing the state of the art technologies in the form of Internet of Things
2 (IoT) and Cyber-Physical System (CPS) [1][4]. Germany is the country which introduced the
3 concept of Industry 4.0, a concept as an embodiment of those new technologies[1]. Together
4 with Japan, Germany has been the leading country in developing manufacturing equipment such
5 as computer numerical control (CNC) machine[5]. The concept will make the future industry
6 more agile and flexible to meet a quickly and constantly changing market demands [6]. From the
7 first introduction in 2011, the concept of Industry 4.0 has been gradually studied, developed and
8 implemented not only in Europe but worldwide. The Indonesian Ministry of Industry introduced
9 a concept of Making Indonesia 4.0 in 2019 [7]. One emphasize of Making Indonesia 4.0 is
10 greater automation in manufacturing technology to increase competitiveness.

11 Recently, the development and application of manufacturing industry technology in Indonesia
12 have been rapidly increasing, as evidenced by the increasingly modern equipment used to work
13 on a product, such as a CNC machine which is a machine that has been equipped with a
14 computer to facilitate the operation of the machine[8][9]. In a few examples, computer
15 technology has been applied to machine tools including lathes, milling machines, scrap machines,
16 and drilling machines[9][10]. The operation of the CNC machine uses a program that is
17 controlled directly by a computer[10]. Hence, the operation of CNC machine tools works by
18 synchronizing the computer and its mechanics[9].

19 Nowadays many industries have begun to abandon conventional machine tools and switch to
20 using CNC machine tools. Quality and productivity aspects are the basic reasons computer-based
21 production machines are widely adopted in the manufacturing industry[11]. Several attributes
22 expected from modern CNC machine include better product quality produced in higher quantity
23 with high speed and precision [12]. The process of synchronizing movements on the axis of
24 motion requires an interpolator system that specifically divides the movements of each axis
25 based on global movement commands which are manifested in the form of motion command
26 signals to the drive system[13][14]. As technology develops, the CNC milling machine
27 conditions must be measured to have reliable performance[14][15]. Afkhamifar et al. conducted
28 research on the analysis of variations for the CNC milling process with results were compared
29 with ISO 2768, a guidelines for general geometrical tolerances and technical drawings[16].The
30 study underlined that the precision of the machine can be improved either by better machine
31 design or software development.

32 The quality of the results of machining processes is quantified by machining performance
33 index which includes milling accuracy and surface quality [12]. The index is affected by the
34 integrated operations of various factors namely CAD/CAM, CNC controller, servo control, feed

1 drive system, and mechanical bodies[12]. Other possible effector which often neglected is probe
2 hysteresis [17] and the subsequent deformation [18]. Improving machining precision has been a
3 widely known challenge in industry as the CNC machine is composed by various moving and
4 rotating shafts that makes machining motion complicated [19]. With regard to milling accuracy,
5 the vibration of the mechanical bodies, sliding motion of stick, and axial motion affect
6 precision[12]. To solve the vibration problem, a real-time resonance signal analysis coupled with
7 online surface quality monitoring has been proposed [20]. Another study suggested kinematic
8 modelling as a method to improve precision of a multi axis CNC machine[19]. Analyzing the
9 complex CNC machine motion has been one of the most important subjects in industrial
10 machining study[19]. Thus, when the researchers at the Research Centre for Electrical Power and
11 Mechatronics, Indonesian Institute of Sciences (RCEPM-LIPI) developed a CNC milling
12 machine, it is important to analyze the machine motion to measure its precision.

13 In a previous study, Zaynawi and Bisono calibrated the X, Y, and Z-axis of the wood CNC
14 router machine using a dial indicator and block gauge[8]. In another study, Wijaya performed
15 calibration of the Y-axis to the accuracy of the workpiece on a 3-Axis CNC Router Machine [21].
16 With regard to the Z-axis, Nayorama, and Sedyono conducted a Z-axis analysis on the
17 calibration process and the movement of the CNC router machine[22]. Fauzi et al. suggested that
18 it is necessary to carry out measurements and analysis of data in every laboratory activity to
19 make a conclusion [23]. Therefore the analysis of measurement uncertainty becomes very
20 important [22][24].

21 From the above-mentioned previous studies, we found out that the respective researchers
22 calibrated the machine that has been calibrated by the manufacturer, whereas in this study, the
23 measurement was performed on a self-designed CNC milling machine developed at RCEPM-
24 LIPI. The objective of this study was to investigate the precision of the CNC milling machine
25 developed at RCEPM-LIPI by measuring how much the deviation of the machine measurement
26 on the X, Y, and Z-axes. The measurement of machining deviation is important in analyzing
27 machine accuracy [25]. The results of this study will serve as the basis for the next process
28 which is calibration, and it is expected that the CNC machine will be able to operate in optimum
29 precision during manufacturing process.

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31 II. Materials and Methods

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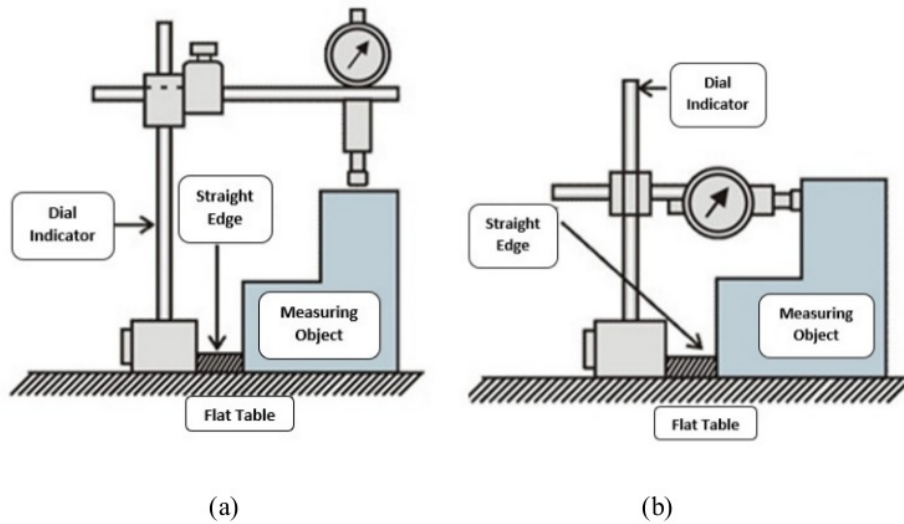
1 A. Straightness Checking

2 Several predictive methods for CNC milling machine maintenance to improve reliability and
3 prevent faults and unnecessary loss have been introduced [26]. The methods include reliability
4 statistics method, physical model-based method, and data-driven method. Reliability statistics
5 method is the simplest method without any mathematical model or detailed information as the
6 method depends on historical deviation data. Physical model-based method uses mathematical
7 model to predict the internal working mechanism through degradation prediction. Data-driven
8 method is the most complicated method which can be performed online. The method is very
9 suitable for complex and expensive equipment manufacturing such as in the aircraft industry.
10 The CNC milling machine developed in RCEPM-LIPI is a simple machine intended for a cheap
11 and easy operation in small and medium enterprises. Therefore the reliability statistics method
12 was considered the most appropriate to assess its precision.

13 The workpiece surface is said to be flat or straight if the results of the measurement of the
14 plane on the surface are straight lines in three-dimensional space as measured by the tangential
15 contact between the tool and the workpiece surface [27]. This means that there are no deviations
16 both horizontally and vertically on the measurement results of a certain distance. Straightness
17 from the surface of a component is very important in machining such as lathes, scrap machines,
18 milling machines, and grinding machines because the work system requires a very precise level
19 of straightness[28]. The skills to make the surface of the workpiece really straight are also
20 necessary, including how to check the straightness itself[24]. In order to measure the
21 straightness/flatness, a straightness check of the X, Y, and Z-axes, as well as leveling checks of
22 the machine table is performed by using a dial indicator, parallel plates, and a flat table[29].

23 The straightness/flatness check on the machine with a dial indicator was performed to
24 understand the magnitude of the deviation. Because any change in the distance experienced by
25 the dial indicator sensor will be designated by the pointer. In order to make the measurements get
26 accurate results, the measurements must be conducted on a flat working table[29]. It is necessary
27 to insert a parallel plate/straight edge between the measuring plane and the dial indicator base to
28 stabilize the dial indicator movement so that a change in the position of the sensor pressure on
29 the measuring plane can be avoided. When placing the sensor on the measuring plane, the
30 pointer should be set to zero. If the measuring plane is relatively long then it should be divided
31 into several sections with the magnitude of the distance of each part is determined first. Between
32 one parts with another marked with a dot or short line/strip. At each of these points later it can be
33 described the magnitude of the deviation from the straightness of the measuring plane. Thus it
34 can be understood which parts of the measuring plane are not straight. Examples of straightness

1 checks are shown in Figure 1. The direction of the horizontal deviation is shown in Figure 1 (a)
 2 and the direction of the vertical deviation is shown in Figure 1 (b). Figure 2 describes the
 3 deviation in the orthogonal axes, namely X-axis (ΔX), Y-axis (ΔY), and Z-axis (ΔZ). The
 4 deviation is defined as the distance between the nominal point (P^n) to the measurement point
 5 (P^m).



8 Figure 1. Straightness checking in (a) the direction of the horizontal deviation (b) the direction
 9 of the vertical deviation.

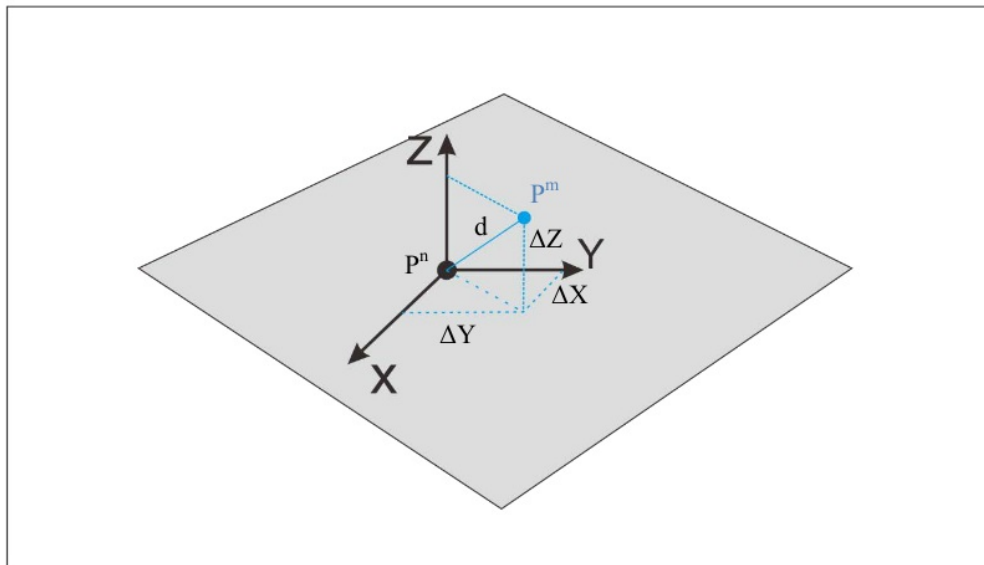
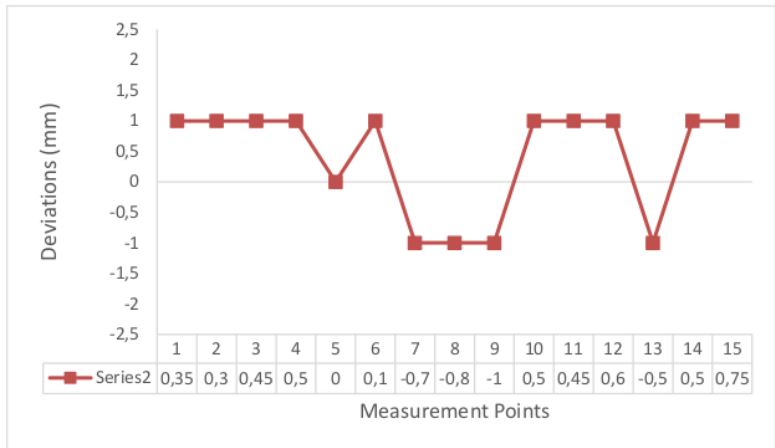


Figure 2. CNC milling machine deviation in the three axis (adapted from Werner, 2018 [25]).

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2 Measurement results and magnitude of deviations are usually illustrated in graphical form
3 with a sign (+) for positive deviations or (-) for negative deviations. Deviations marked positive
4 or negative are based on allowed threshold values. If the inspection result turns out to exceed the
5 allowed threshold values, it can be said that the level of straightness of the measuring object is
6 not good or low, regardless of whether the deviation is positive or negative. An example of the
7 results of the straightness checks in the form of a line graph is illustrated in Figure 3.



8

9 Figure 3. The results of the surface straightness check of the measuring object using the dial
10 indicator.

11 The above method is suitable for examining the side of a measuring plane that is relatively
12 narrow and its direction extends (the thick side of the measuring object). If the measuring plane
13 is wide enough in the extended direction then the straightness check can be carried out several
14 times in different positions according to considerations that are more favorable in the
15 measurement process. So, the examination is not only on one line but can be more than one
16 line[23].

17 B. Object Specifications, Instruments, and Measurement Methods

18 The object to be measured is a prototype 3 axis CNC Milling Machine as a result of the
19 research and development of RCEPM-LIPI (Figure 4). The CNC milling machine that will be
20 measured has the following specifications:

- 21 1. Maximum spindle speed = 12,000 rpm.
- 22 2. Stroke of the X-axis = 180 mm, Y-axis = 160 mm and Z-axis = 200 mm.
- 23 3. Servo motor power used for X, Y, and Z axes = 400 W.

- 1 4. The maximum diameter of the chisel can be used on a spindle = 6 mm.
- 2 5. Maximum workpiece material = aluminum.



3

4 Figure 4. The prototype of 3-axis CNC Milling Machine developed at RCEPM-LIPI.

5 While the equipment used in this measurement process is as follows:

- 6 1. Parallel Plates or flat part of the machine on the horizontal and vertical sides.
- 7 2. Clamping.
- 8 3. Dial Indicator with a level of accuracy of 0.05 mm.

9 Dial indicator or dial gauge is used to measure bending, run out, slackness, end play, backlash,
10 and flatness. Inside the dial indicator, there is a mechanism that can magnify the small
11 movements. When the spindle moves along the measured surface, the movement is magnified by
12 a magnifying mechanism and then indicated by the pointer. The procedure for using the dial
13 indicator is as follows:

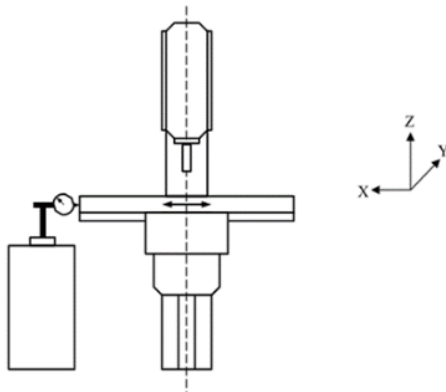
- 14 1. The spindle dial indicator position must be perpendicular to the measured surface.
- 15 2. The line of imagination from the measuring eye to the pointer must be perpendicular to
16 the dial indicator surface while reading the measurement results.
- 17 3. The dial indicator must be installed carefully on the supporting rod, meaning that the dial
18 indicator must not shake.
- 19 4. Turn the outer ring and set it to zero. Move the spindle up and down, then check that the
20 pointer always returns to zero after the spindle is released.

- 1 5. Observe and record the changes that occur in the indicator dial pointer for each
- 2 measurement point, which is every 15 mm.
- 3 6. If the measurement has been completed up to 13 times or the last point then return the
- 4 position of the dial indicator to its original position by moving in the direction of the X-
- 5 axis, Y-axis, or Z-axis being measured.

7 III. Results and Discussion

8 A. X-axis Measurements

9 The measurement process on the CNC milling machine designed and developed at RCEPM-
 10 LIPI was carried out on its three axes, namely the X, Y, and Z axes. The data collection scheme
 11 on the X-axis is shown in Figure 5. X-axis measurement was carried out 3 times where each
 12 process was carried out by measuring 12 measurement points. The X-axis measurement results
 13 are displayed in tabular and graphical form as shown in Table 1 and Figure 6.



14
 15 Figure 5. Scheme of deviation measurement at X-axis[10].

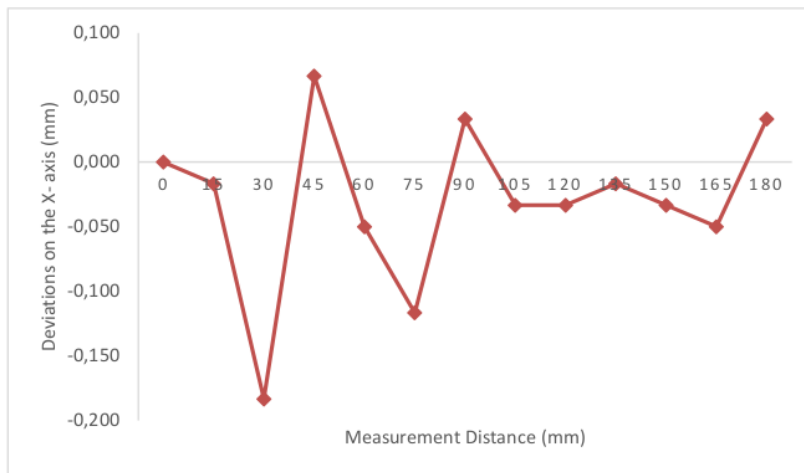
16 Table 1. X-axis measurements results.

NO	Measurement Distance (mm)	Deviations (mm)			Average Deviation(mm)
		1	2	3	
	0	0,00	0,00	0,00	0,000
1	15	-0,15	0,20	-0,10	-0,017
2	30	-0,30	-0,15	-0,10	-0,183
3	45	0,25	0,15	-0,20	0,067
4	60	-0,15	0,10	-0,10	-0,050
5	75	-0,10	-0,15	-0,10	-0,117
6	90	-0,15	0,10	0,15	0,033
7	105	0,10	-0,10	-0,10	-0,033
8	120	-0,10	0,15	-0,15	-0,033

9	135	-0,15	0,20	-0,10	-0,017
10	150	-0,20	0,20	-0,10	-0,033
11	165	-0,15	-0,15	0,15	-0,050
12	180	0,10	0,10	-0,10	0,033
Average					-0,033

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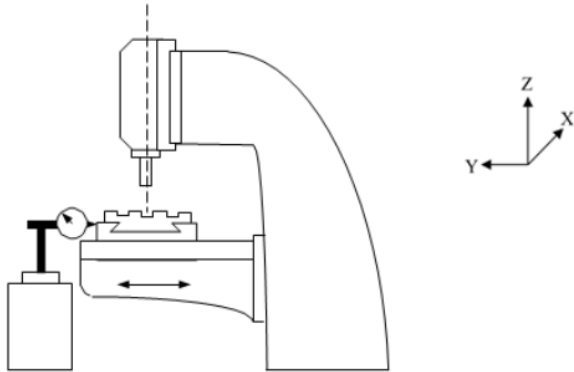
4 Figure 6.X-axis deviation graph. The maximum deviation occurred at the second point of 30
5 mm measurement distance (-0.183 mm), while the minimum deviation of -0.017 mm occurred at
6 the first (15 mm measurement distance) and the ninth points (135 mm measurement distance).

7 Table 1 and Figure 5 show that the maximum deviation on the X axis is -0.183 mm at the
8 second test point. The smallest deviation is at the testing points 1 and 9 that are -0,017 mm. The
9 average deviation is -0,033 mm. The minus sign means the measured area is away from the
10 indicator needle while the positive sign means the measured field is close to the indicator needle.
11 Compared to previous studies, the results in this study is lower than a study by Afkhamifar et al.
12 whose position error of X-axis was 0.134 mm at average value [16] and in the range of
13 acceptable deviation which a reference suggested between -0.030 mm to +0.045 mm [25].
14 However compared with the higher precision of CNC machine with laser measuring system, the
15 average deviation is higher [24].

16 B. Y-axis Measurements

17 The process of measuring a CNC milling machine using the indicator dial on the Y-axis is
18 depicted in Figure 7. Y-axis measurement was carried out 3 times where each measurement was

1 performed on 10 measurement points. Y-axis measurement results are shown in Table 2 and
 2 Figure 8.

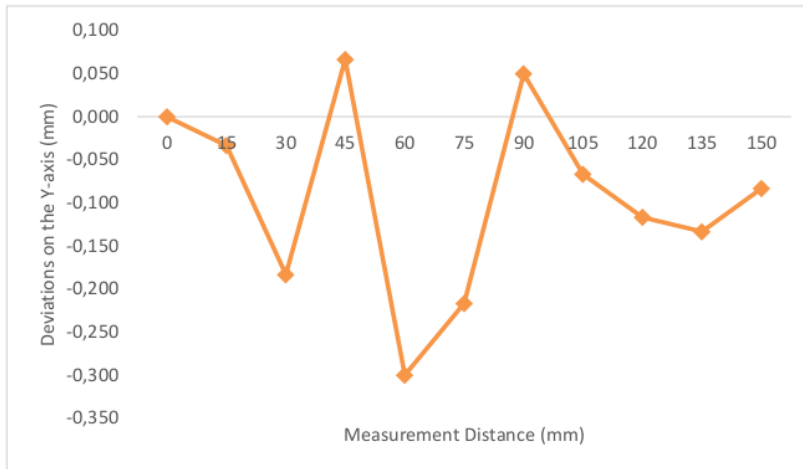


3
 4 Figure 7. Scheme of deviation measurement at Y-axis[10].

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 6 Table 2. Y-axis measurements results.

NO	Measurement Distance (mm)	Deviations (mm)			Average Deviation (mm)
		1	2	3	
	0	0,00	0,00	0,00	0,000
1	15	-0,20	0,40	-0,30	-0,033
2	30	-0,20	-0,10	-0,25	-0,183
3	45	0,20	0,15	-0,15	0,067
4	60	-0,25	-0,25	-0,40	-0,300
5	75	-0,15	-0,25	-0,25	-0,217
6	90	-0,35	0,25	0,25	0,050
7	105	0,20	-0,25	-0,15	-0,067
8	120	-0,15	0,15	-0,35	-0,117
9	135	-0,35	0,20	-0,25	-0,133
10	150	-0,25	0,20	-0,20	-0,083
Average					-0,102

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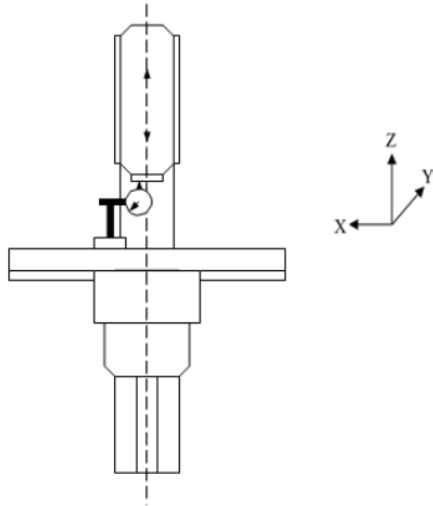
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2 Figure 8.Y-axis deviation graph. The maximum deviation occurred at the fourth test point of
 3 60 mm measurement distance (-0.300 mm), while the minimum deviation occurred at the second
 4 test point of 15 mm measurement distance (-0.033 mm).

5 As described in Table 2 and Figure 8,the maximum deviation on the Y axis is -0,300 mm at
 6 the fourth test point. The smallest deviation is at the second test point that is -0,033 mm. The
 7 average deviation is -0,102 mm. The minus sign means the measured area is away from the
 8 indicator needle while the positive sign means the measured field is close to the indicator
 9 needle.The deviation in Y-axis is greater than the previous studies which reported average
 10 deviation at Y-axis is 0.056 mm [16].

11 C. Z-axis Measurements

12 The scheme of measuring the CNC milling machine on the Z-axis is illustrated in Figure 9.
 13 Measurements on the Z-axis were carried out 3 times wherein each process measurements were
 14 made of 10 measurement points. Z-axis measurement results are shown in Table 3 and Figure 10.



1

2 Figure 9. Scheme of deviation measurement at Z-axis[10].

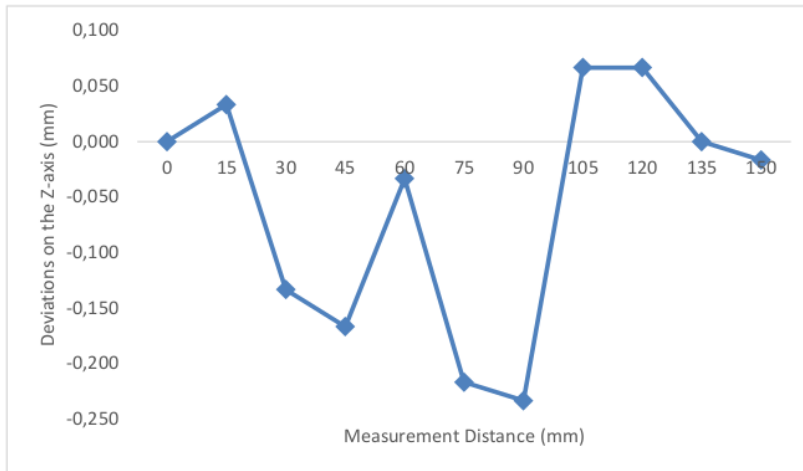
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4 Table 3. Z-axis measurements results.

NO	Measurement Distance (mm)	Deviations (mm)			Average Deviation (mm)
		1	2	3	
	0	0,00	0,00	0,00	0,000
1	20	0,15	-0,15	0,10	0,033
2	40	-0,10	-0,10	-0,20	-0,133
3	60	-0,15	-0,15	-0,20	-0,167
4	80	0,25	-0,15	-0,20	-0,033
5	100	-0,15	-0,25	-0,25	-0,217
6	120	-0,20	-0,25	-0,25	-0,233
7	140	-0,15	0,15	0,20	0,067
8	160	0,15	-0,15	0,20	0,067
9	180	0,10	0,15	-0,25	0,000
10	200	-0,15	0,25	-0,15	-0,017
Average					-0,063

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2 Figure 10.Z-axis deviation graph. The maximum deviation occurred at the sixth test point of
 3 90 mm measurement distance (-0.233 mm), while the minimum deviation occurred at the ninth
 4 test point of 135 mm measurement distance (0 mm).

40

5 Table 3 and Figure 10 present the measurement results of the deviation at Z-axis.The
 6 maximum deviation on the Z-axis is -0.233 mm at the sixth point test. The smallest deviation is
 7 at the ninth test point that is equal to 0 mm. The average deviation is -0,063 mm. The minus sign
 8 means the measured area is away from the indicator needle while the positive sign means the
 9 measured field is close to the indicator needle.The average deviation of Z-axis is larger than the
 10 previous study which resulted a deviation at Z-axis of -0.021 mm[16], and much larger than the
 11 previous study using laser measuring system whose largest deviation at Z-axis only 0.004 mm
 12 [24].

13 D. Flatness of the Machine Base Table

14 In addition to measuring the straightness of the three working axes of the CNC Milling
 15 Machine designed at RCEPM-LIPI, a measurement process was also carried out on the flatness
 16 of the machine base table. The schematic that shows data collection from the measurement of the
 17 flatness of the machine table is depicted in Figure 11. The measurement of the machine table
 18 flatness was also carried out 3 times with each process measuring 10 measurement points. The
 19 CNC Milling Machine table measurement results are shown in Table 4 and Figure 12.



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2 Figure 11. Test scheme on the machine table.

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4 Table 4. Machine table flatness measurement results.

NO	Measurement Distance (mm)	Deviations (mm)			Average Deviation (mm)
		1	2	3	
	0	0,00	0,00	0,00	0,000
1	15	-0,50	0,10	-0,10	-0,167
2	30	-0,10	-0,15	-0,15	-0,133
3	45	0,15	0,10	-0,15	0,033
4	60	-0,10	-0,15	-0,15	-0,133
5	75	-0,15	-0,20	-0,20	-0,183
6	90	-0,20	-0,20	-0,15	-0,183
7	105	0,10	0,10	-0,10	0,033
8	120	-0,10	-0,15	-0,20	-0,150
9	135	0,15	0,20	0,10	0,150
10	150	0,20	-0,20	-0,15	-0,050
11	165	-0,25	-0,25	-0,15	-0,217
12	180	-0,15	-0,15	-0,15	-0,150
Average					-0,096

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2 Figure 12. Machine table flatness deviation graph.

3 Table 4 and Figure 12 show that the maximum deviation on the X axis is -0.217 mm at the
 4 eleventh point test of 165 mm measurement distance. The smallest deviation is at the third test
 5 point at 45 mm measurement distance that is equal to 0.033 mm. The average deviation is -0.096
 6 mm. The minus sign means the measured area is away from the indicator needle while the
 7 positive sign means the measured field is close to the indicator needle.

8 From the X, Y, Z, and flatness measurements, it is known that the deviation values: the
 9 average X axis deviation is -0.033 mm, Y -0.102 mm axis, Z -0,063 mm, and -0.096 mm flatness.
 10 The value of the deviation is still within the limits of the tolerance standard set at ISO 2768.
 11 These results are almost the same when compared with previous studies conducted by
 12 Afkhamifar et al. where in his research it was found that the results of the X, Y, and Z axis
 13 deviations were 0.134 mm, 0.056 mm, and -0.021 mm, respectively [16].

14 While the results are acceptable by ISO 2768 standard, the deviation at Y-axis and Z-axis are
 15 relatively greater than the comparable previous study which indicates improvement for the
 16 developed CNC milling machine is necessary. There are several possible causes that produced
 17 inaccuracy in this study as suggested by the previous study [16]. The first possibility comes from
 18 the machine table which plays a role as a base. The second possibility comes from the upper
 19 body of the machine. The third possibility comes from the head and the last possibility comes
 20 from the interaction between the base and the workpiece. These shortcomings require better
 21 machine design as suggested by the previous study [16]. Other solutions include the application
 22 of better software [16][29], more complex yet reliable mathematical modelling [30], or more
 23 precise sensors such as real-time vibration monitoring [20], transducer in a kinematic probe [17],
 24 or laser measuring systems [24]. Furthermore, as a technology driven product research, the

1 design and development phase of CNC milling machine often neglects the interdisciplinary
2 approach, especially from industrial and human factors studies [31]. The design of a machine
3 without the consideration of the human factors often leads to human error and faults in
4 operation beside the limitation technical performance from the machine technology.

5

6 **IV. Conclusions**

7 The measurement results of the CNC Milling machine developed at RCEPM-LIPI in Bandung
8 show that the CNC Milling machines have deviations on each axis, including the X-axis of 0.033
9 mm, the Y-axis of 0.102 mm, the Z-axis of 0.063 mm, and the flatness of the table 0.096 mm.
10 The results are in acceptable performance limitation required by ISO 2768. Based on these
11 measurements, this CNC Milling machine can be used for machining work processes that can
12 move together on 3 axes namely X, Y, and Z axes where the machine can be used to make
13 components that have tolerances above 0.1 mm. However future manufacturing needs may
14 require even higher precision and the developed CNC milling machine still has quite high
15 inaccuracy compared to several previous studies. The application of Industry 4.0 concept as well
16 as more sophisticated sensors, mathematical modelling, data processing, and software are
17 necessary for future study.

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